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GRB localization by timing in LEO

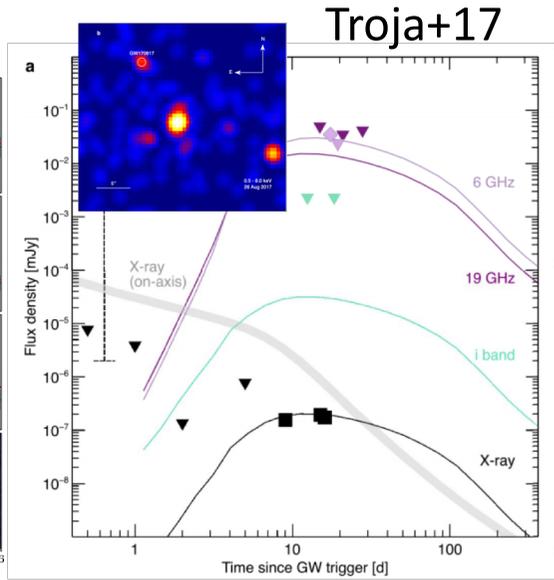
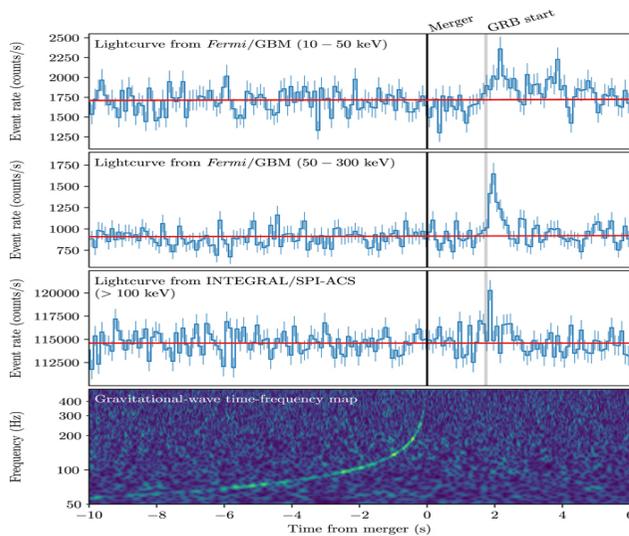
Masanori Ohno (Hiroshima University)



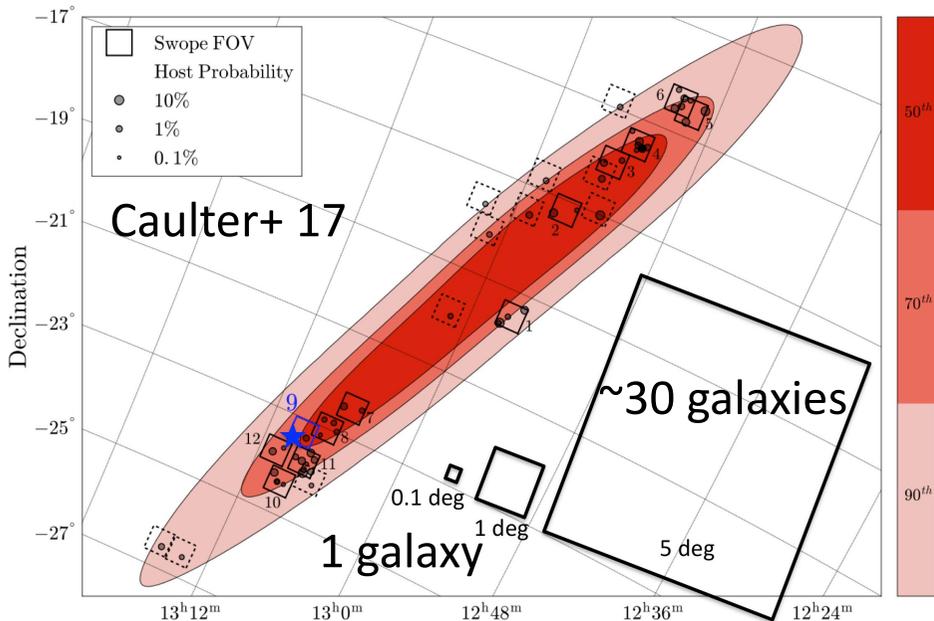
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Localization of GRBs :

a key for the future MM astronomy



- EM counterpart from NS-NS merger event **GW170817/GRB170817A**
- Gigantic campaign of follow-up observation in many EM wavelengths successfully carried out
- short GRB association is still unambiguous



Large FoV (all-sky)

+

good localization

(tens arcmin : FoV of future opt.

telescopes

~arcsec : unique candidate constraint)

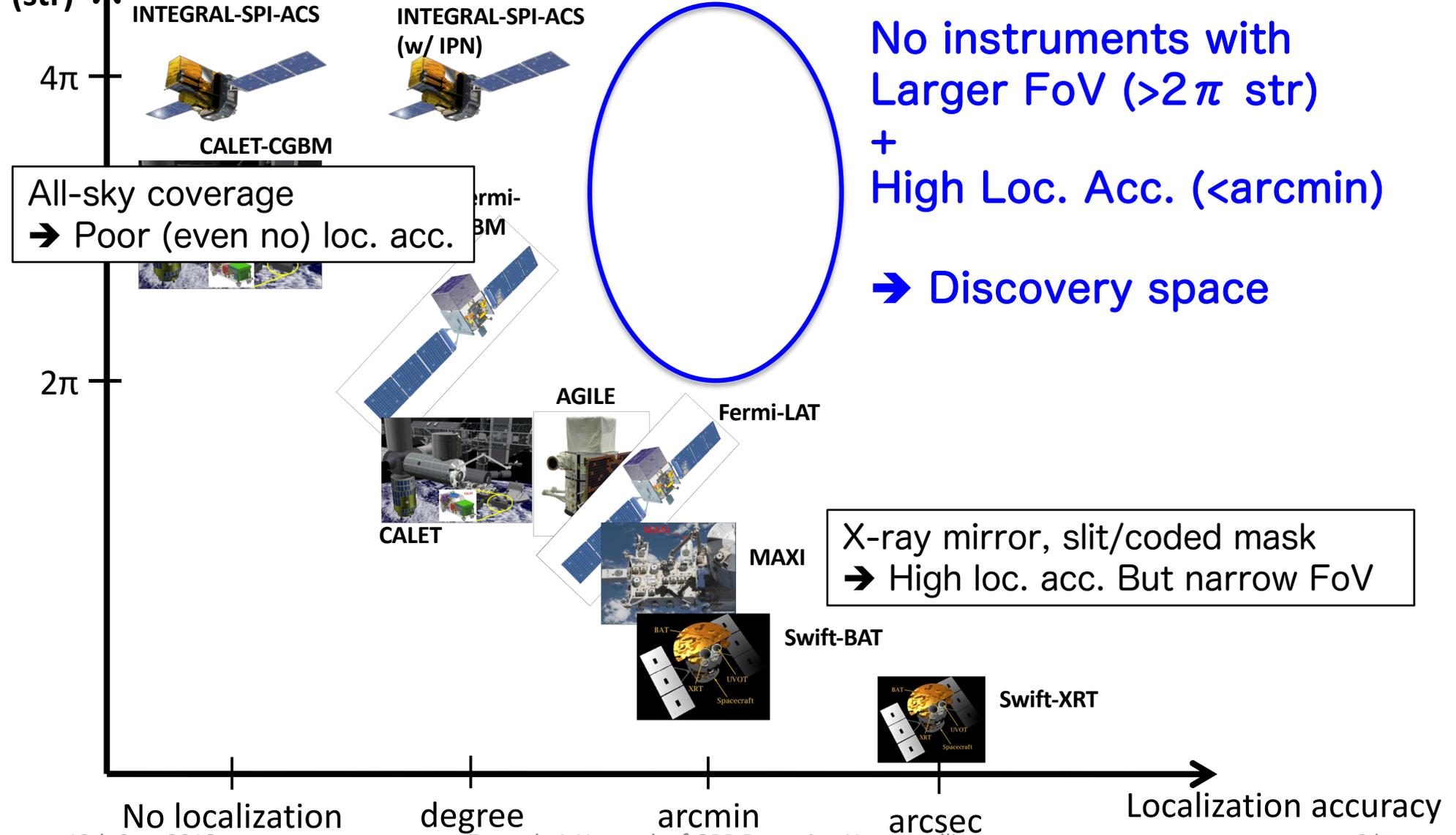


What do we need ?

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Field of view

(str)





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A localization method view

Field of view

(str) ↑

4π

Timing-based
localization

Detector-sensitivity
-based localization

2π

tracking-based
Localization
(high-E gamma)

imaging-based
localization

Imaging of mask/slit
patterns

X-ray source
imaging

No localization

degree

arcmin

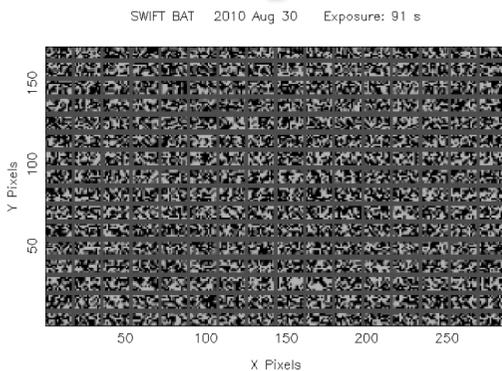
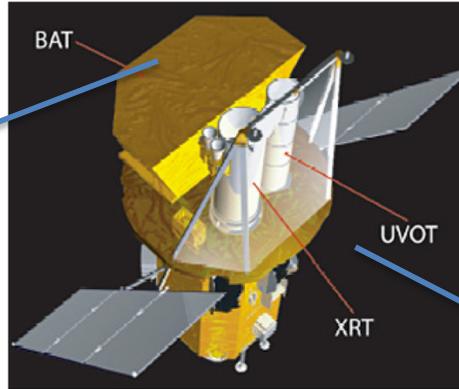
arcsec

Localization accuracy →

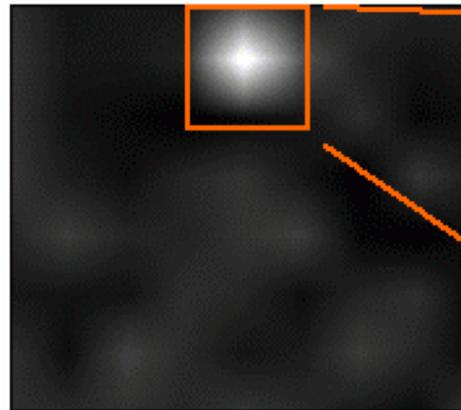


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Imaging-based localization

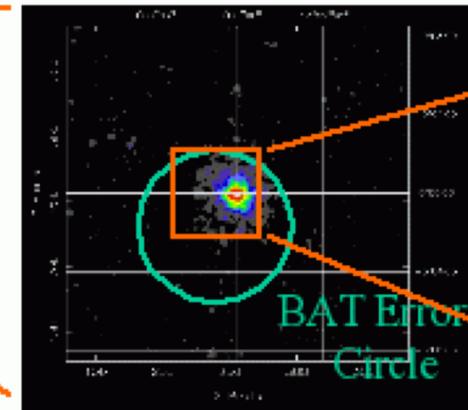


BAT Burst Image



$T < 10$ sec

XRT Image



$T < 90$ sec

- Simple localization by imaging (direct image or mask/slit patterns)
- Excellent positional accuracy (arcsec-arcmin), but a limited field of view ($< \sim 1$ str)

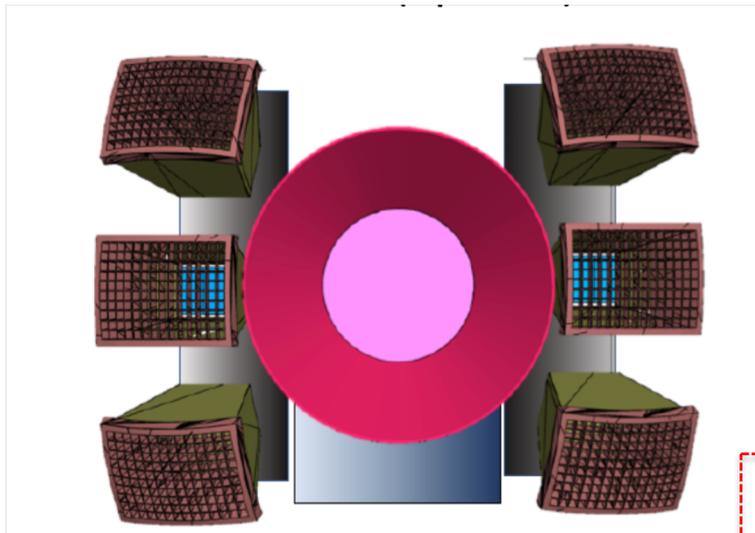


Lobster-eye optics : imaging+large FoV

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Future missions for realizing the good (arcmin) imaging localization with larger FoV are proposing

High-Z Gamma-ray bursts for UNraveling the Dark Ages (HiZ-GUNDAM) : Japan



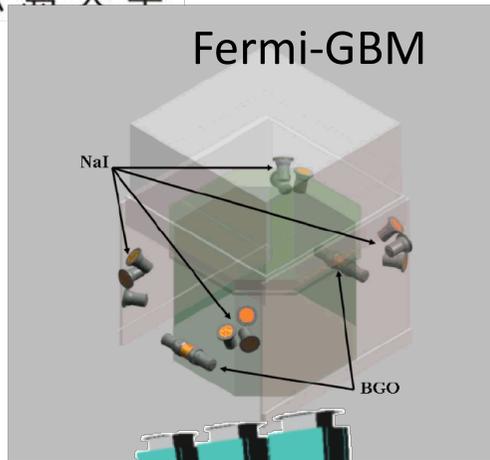
Energy band (keV)	0.5 – 4 keV
Telescope type:	Lobster Eye Optics
Optics aperture	240 x 320 mm ²
Optics configuration	6 x 8
Size of Lobster Eye optics	40 x 40 mm ²
Focal length	300 mm
Focal plane shape	spherical
Focal plane detectors	CMOS array
Size of Focal detector	120 x 160 mm ²
Number of CMOS	24 (4 CMOS x 6 units)
Pixel size	20 – 50 μm
Pixel Number	6000 x 8000 for 20 μm 2400 x 3200 for 50 μm
Field of View	~ 0.2 str X6=1.2 str
Angular accuracy	~ 60 arcsec

Similar concept is proposed by ESA :Transient High-Energy Sky and Early Universe Surveyor (Theseus)
Expect to improve the FoV of imaging localization, but still not cover the “all-sky”

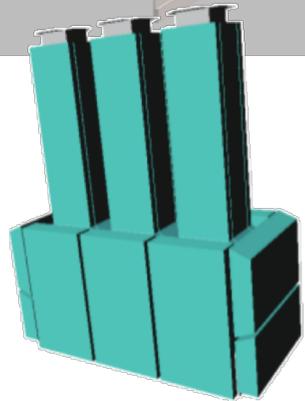
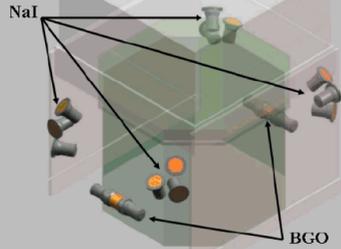


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Detector-sensitivity-based localization

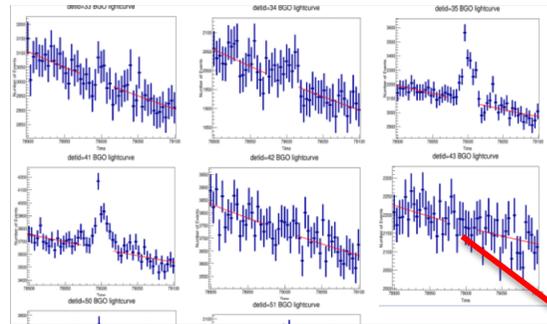


Fermi-GBM

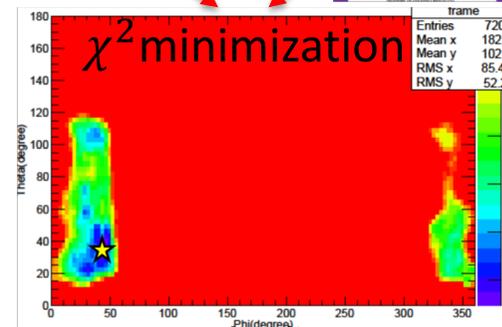
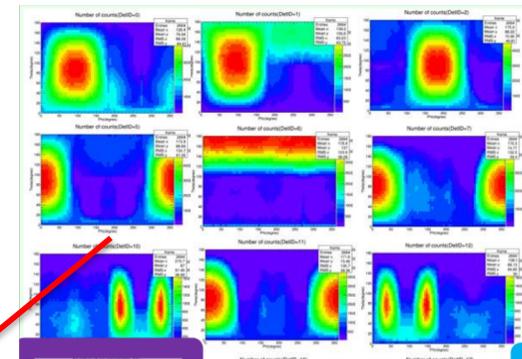


Hitomi-SGD-shields

Observed counts for Each detector



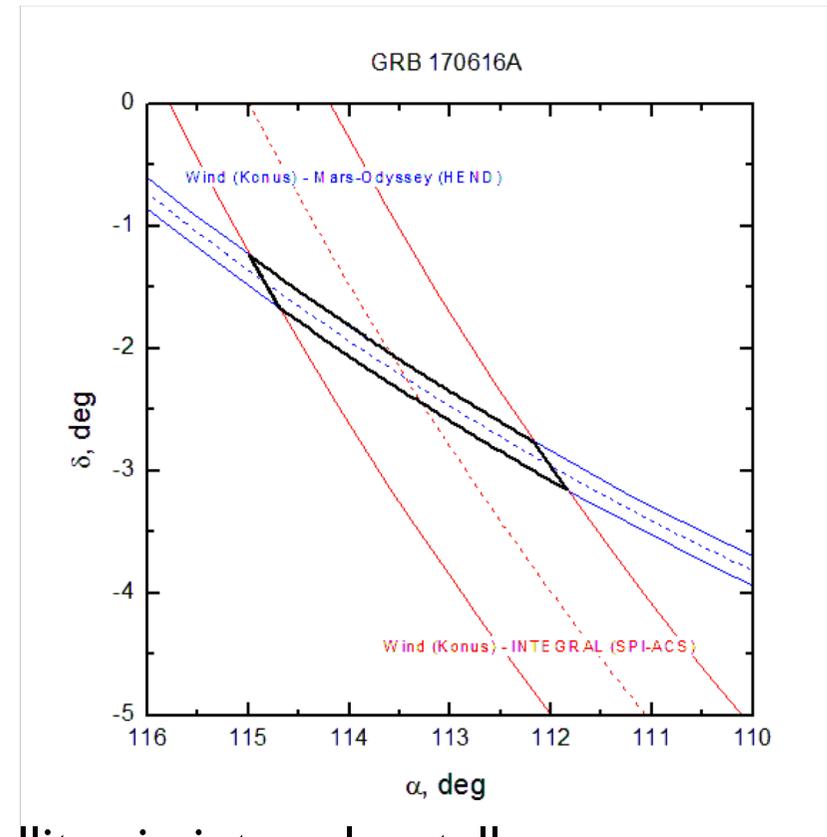
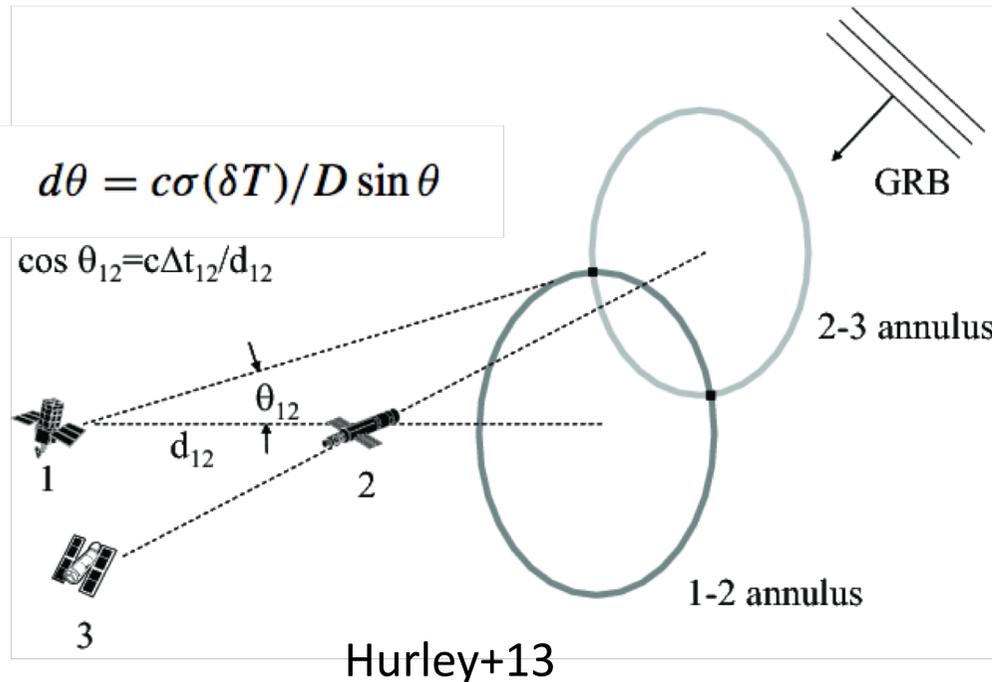
Predicted counts from various incident directions



- Comparison of detected counts and the modeling for detectors with various orientations
- Nice FoV (almost all-sky), and moderate localization (several degs)
- Systematic uncertainty (modeling of background, detector response ..etc.) is a limiting factor



Timing-based localization



- “Triangulation” by several long-distant satellites in inter-planetary space
- Since 1976 and ongoing
- Long baseline gives a good localization (arcmin~deg) but difficult to synchronize the timing between different satellites.
- Very long data acquisition latency (>days)



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How to achieve the all-sky+arcmin localization ?

Field of view (str) ↑

4π

2π

w/ good timing sync.
w/ large number of sat.

Our direction:
All-sky + arcmin
localization

Timing-based
localization

Detector sensitivity
Single satellite
→ earth shadow
Complicated detector
modeling

Single satellite
→ earth shadow
Too narrow FoV

(high-E gamma)

imaging-based
localization

Imaging of mask/slit
patterns

X-ray source
imaging

No localization

degree

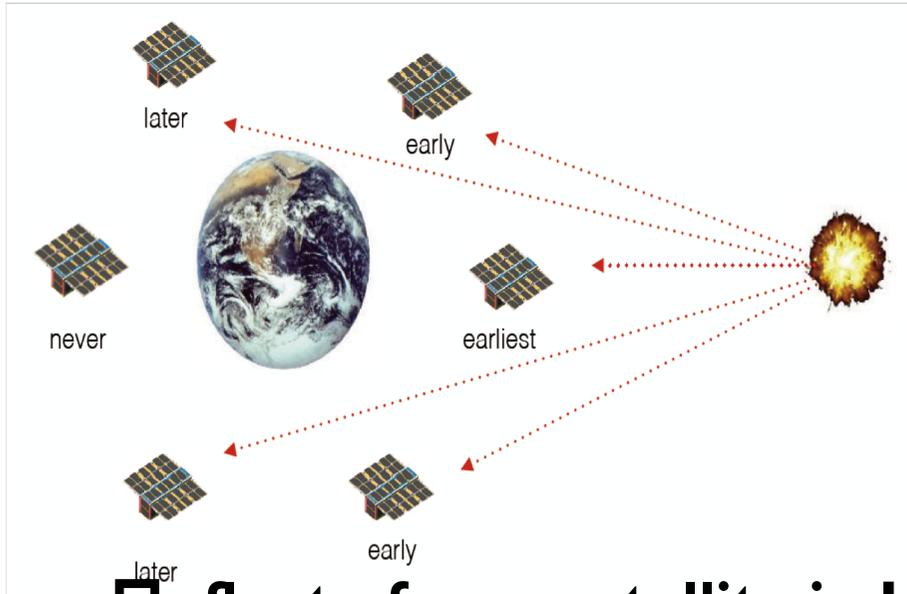
arcmin

arcsec

Localization accuracy →



timing-based localization + Fleet of nanosatellite in LEO



□ timing-based localization
with high timing
synchronization accuracy

$$d\theta = c\sigma(\delta T)/D \sin \theta \quad \text{Hurley+13}$$

GPS < 100 us sync. accuracy (Pal+18) → arcmin
Localization accuracy

□ fleet of nanosatellite in LEO

- all-sky coverage
(no earth shadow)
- large satellite number gives a better localization accuracy
→ good to think about data sharing for each smallsat project
- better latency than IPN

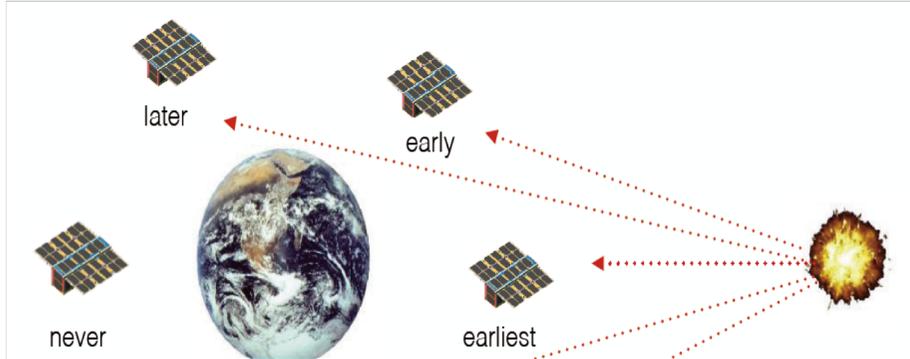
$$\sigma_{Pos} = \sigma_{CCF} \times c / \langle B \rangle / (N - 1 - 2)^{1/2}$$

Taken from F. Fiore's slide

100 satellites collaboration
→ Arcsec localization !?



timing-based localization + Fleet of nanosatellite in LEO



□ timing-based localization
with high timing
synchronization accuracy

$$d\theta = c\sigma(\delta T)/D \sin \theta \quad \text{Hurley+13}$$

Can we really realize such a good localization even if we take into account the realistic photon statistics and detector response for the nanosatellite ?

- all-sky coverage
(no earth shadow)
- large satellite number gives a better localization accuracy
→ good to think about data sharing for each smallsat project
- better latency than IPN

$$\sigma_{Pos} = \sigma_{CCF} \times C / \langle B \rangle / (N - 1 - 2)^{1/2}$$

Taken from F. Fiore's slide

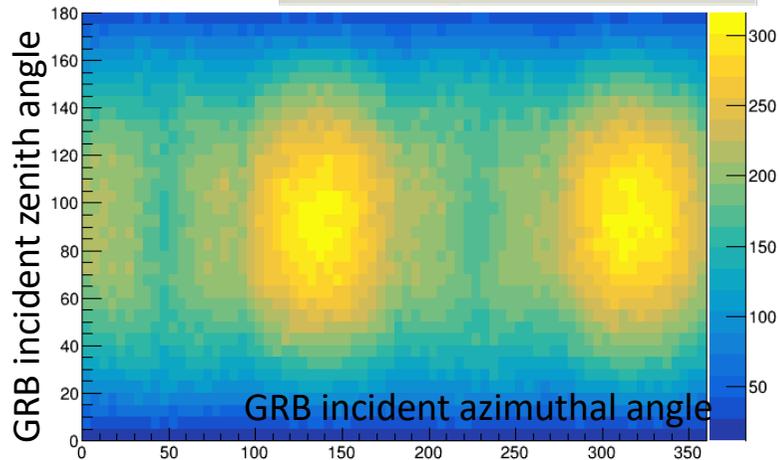
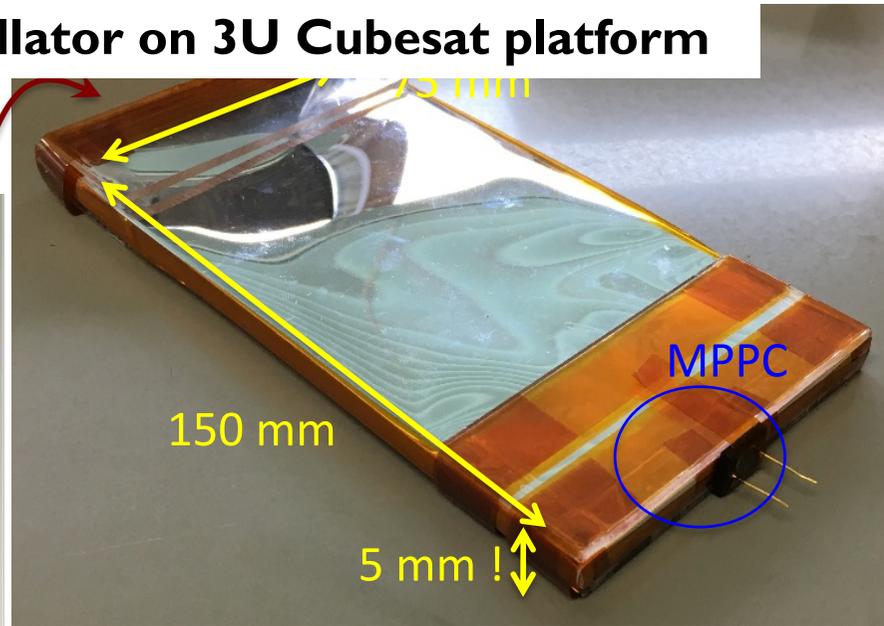
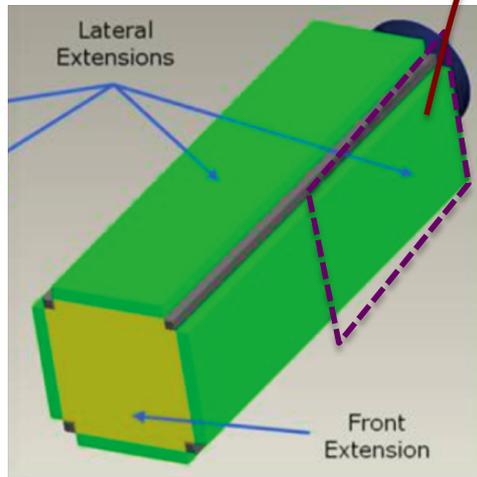
100 satellites collaboration
→ Arcsec localization !?



Timing-based localization w/ nanosats : feasibility ?

Assumed Detector design:

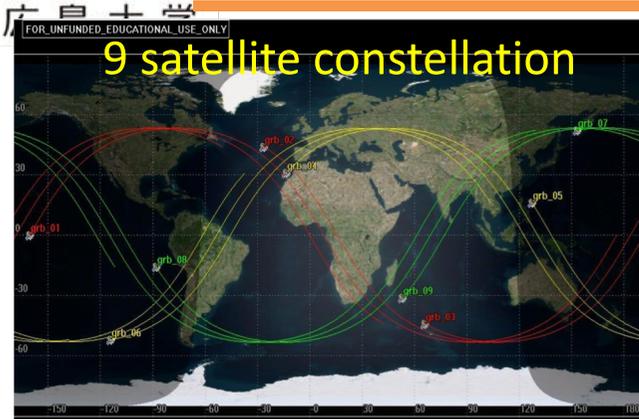
4 large-thin plates of CsI scintillator on 3U Cubesat platform



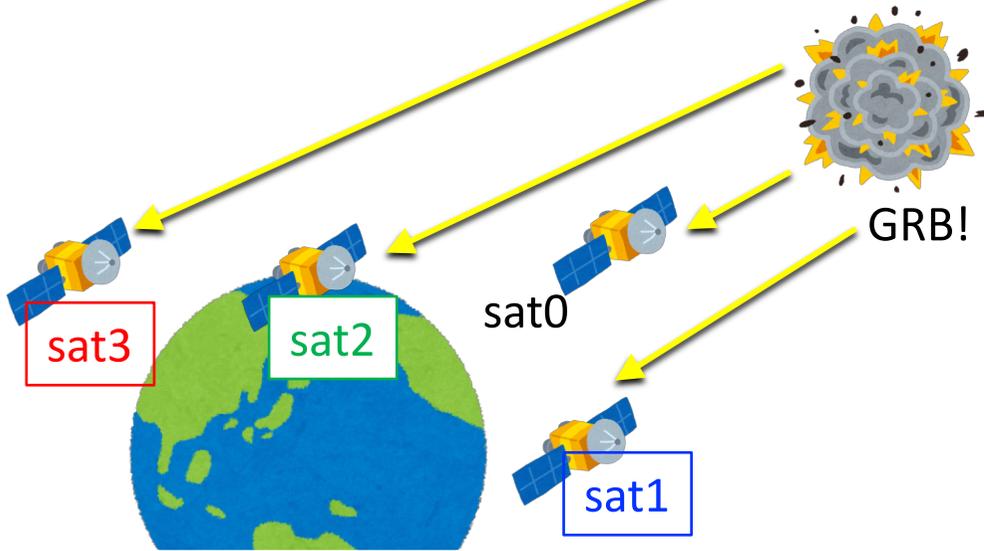
A simple single cubesat design realizes a comparable effective area to Fermi-GBM (~300cm² at good incident angles) with an energy range of 10 to 1000 keV



Localization feasibility



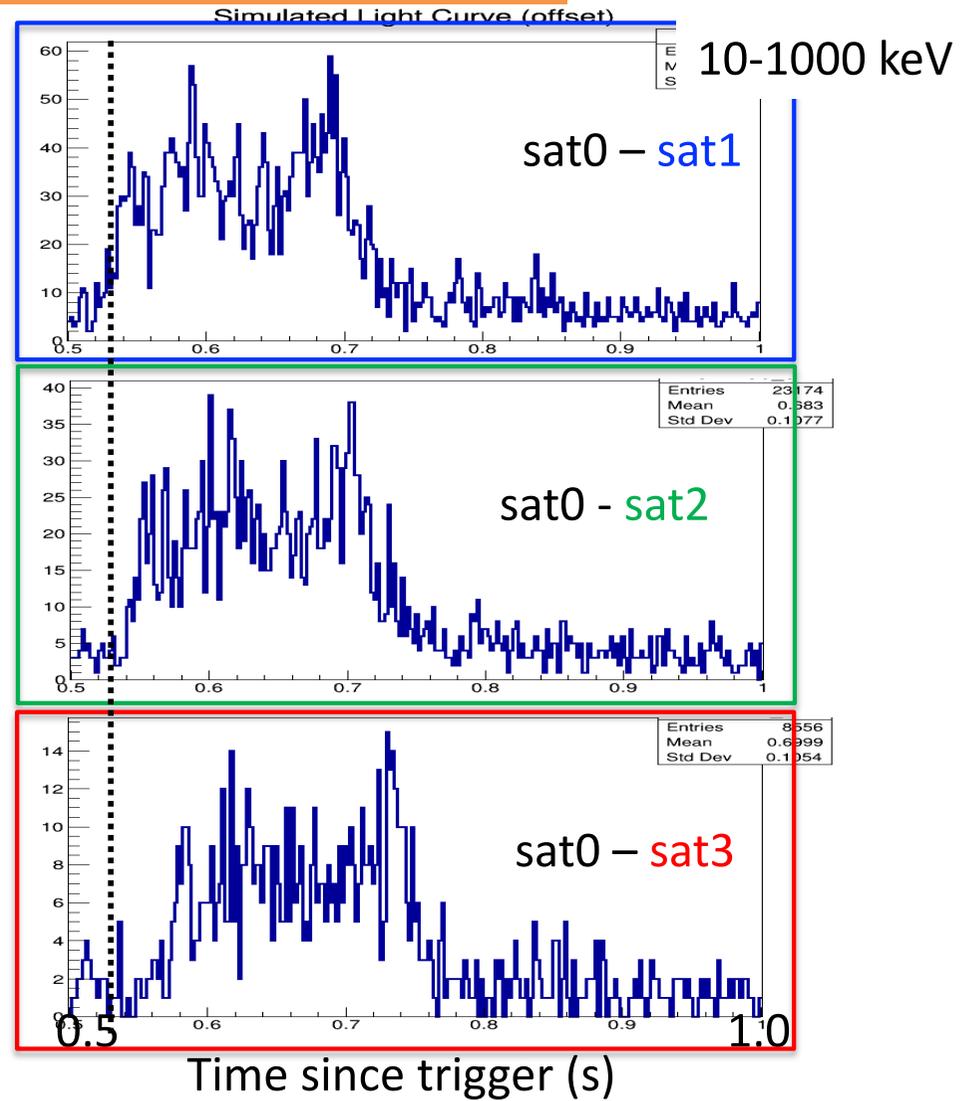
Semi-major axis:
6878.14 km
Inclination:
53 degree
RAAN:
0, 120, 240
True Anomaly:
0~320
(40 deg step)



Satellite attitude, GRB position, predicted photon count/arrival time can be estimated by orbital and detector simulations.

13th Sep. 2018

Towards A Network of G



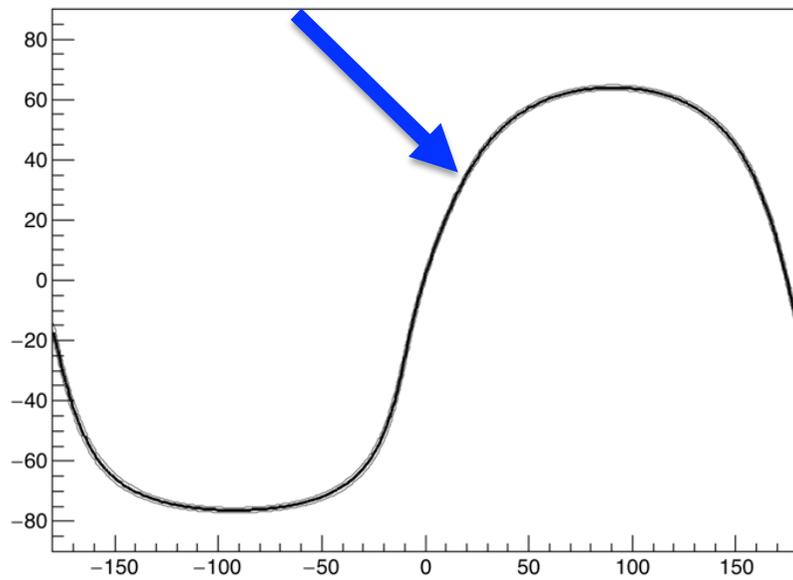
Simulated photon arrival time is estimated by the cross correlation analysis → triangulation annulus



Localization !

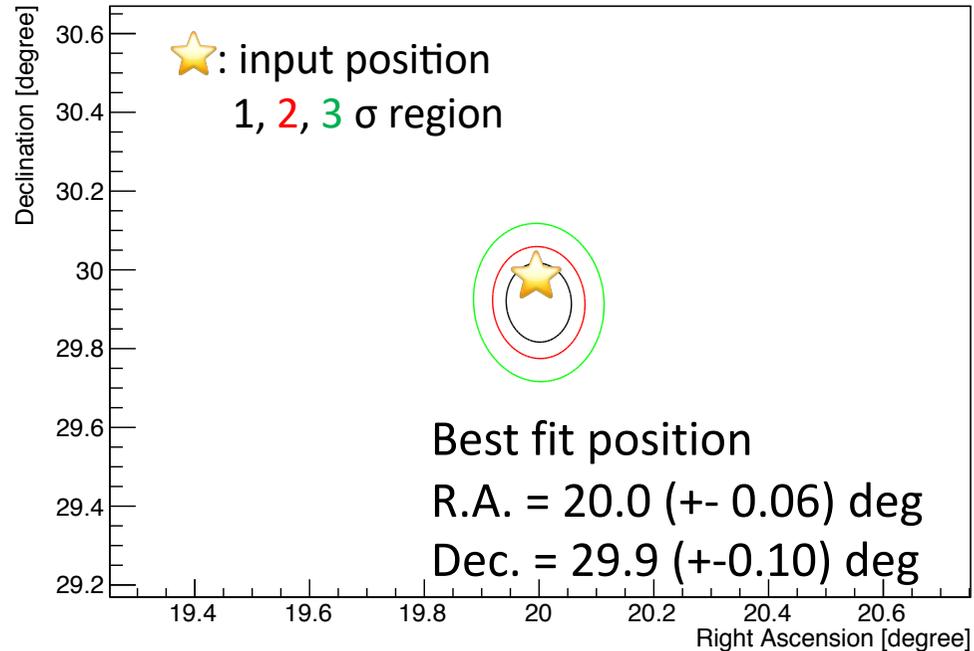
Example for a bright (GRB*** fluence:** erg cm-2, T90=**s) and good-visibility (detected by 9 satellites) case

deltaTMap1



Simple χ^2 minimization

$$\chi^2 \equiv \sum_{i=0}^N \frac{\left\{ \delta t_{sim,i} - Norm \times \cos\theta_{model,i}(R.A., Dec.) \times D/c \right\}^2}{\sigma_{sim,i}^2},$$



**~0.1 deg_{1σ} (~10 arcmin)
accuracy is achievable for
bright/good-visibility case**

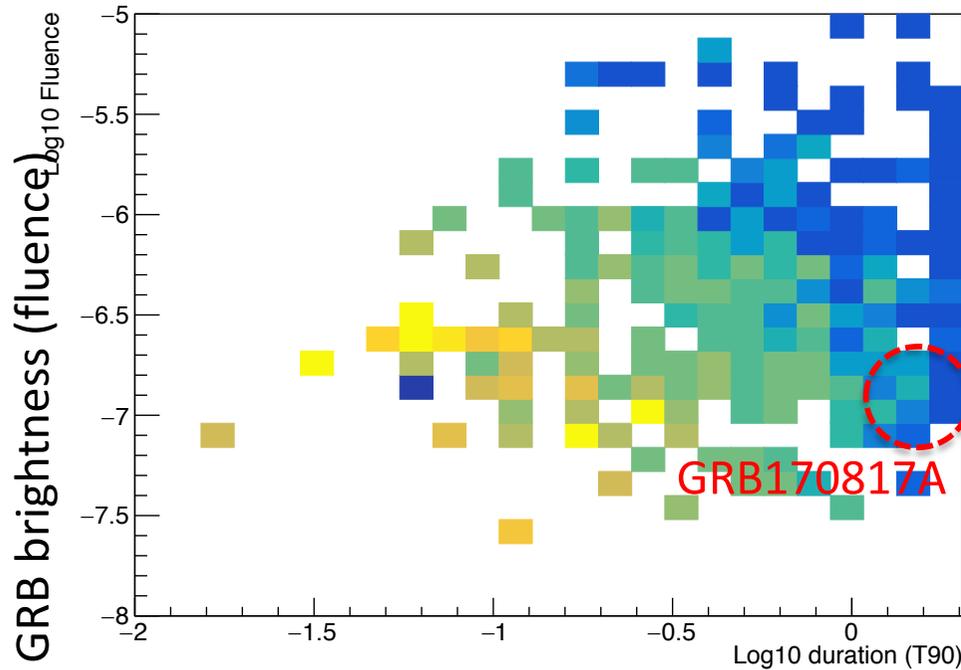


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Systematic analysis for Fermi-GBM short GRB

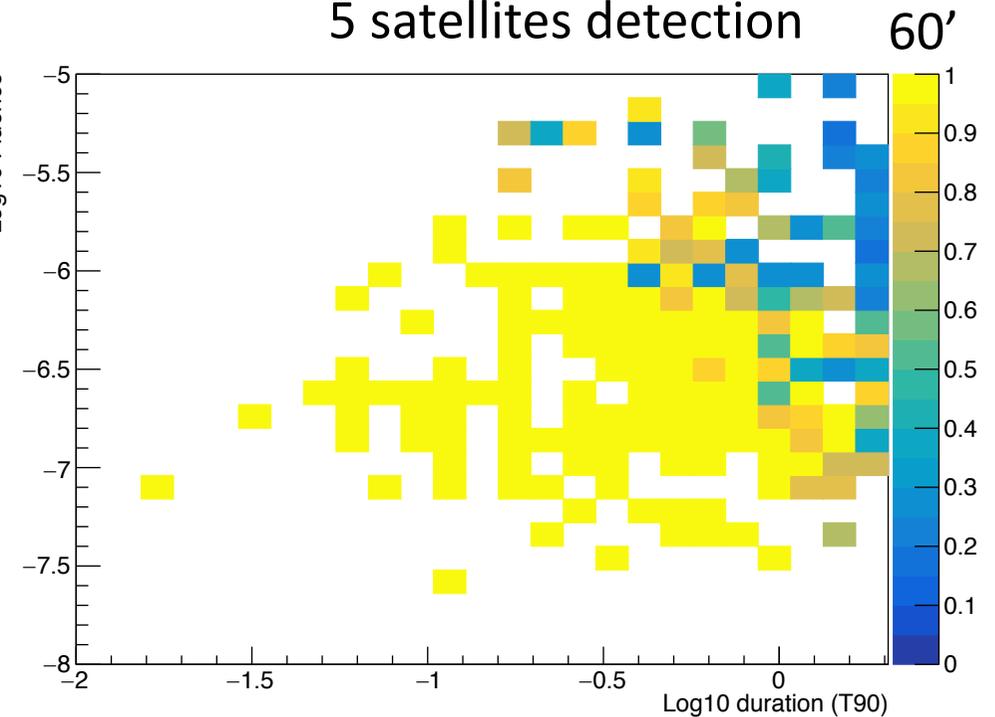
Localization accuracy of this concept is examined for all short GRBs listed in Fermi 3rd GRB Catalog (Bhat+16 $T_{90} < 2s$: 326 samples)

9 satellites detection



GRB duration

5 satellites detection



60'

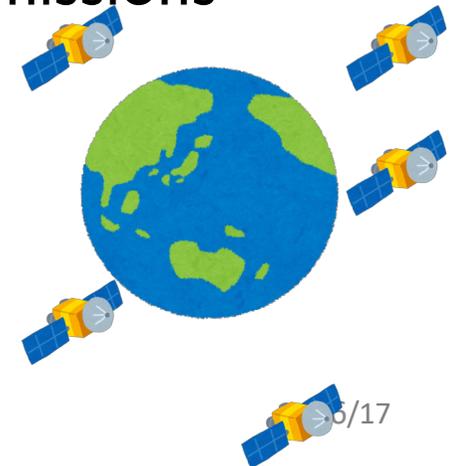
- High localization accuracy for good photon statistics (brighter/longer)
- Larger number of satellite gives a better localization
- 5-10 arcmin accuracy for good conditions



Summary

- X-ray/Gamma-ray follow-up of GW counterpart is important for revealing the nature of their sources
- Timing-based localization is a good candidate to realize a arcmin localization with all-sky coverage
- A first stage of the feasibility study shows a nice outlook for this concept
- Increasing the participating satellite would improve the localization accuracy
- Collaboration (data sharing ..etc.) of small satellite missions could be a future direction of GRB localizations

Let's enjoy sharing mission information and discussions !





Event rate and localization

Sat. num.	Visibility prob.	Number ratio of Fermi sGRB for each localization accuracy		
		loc. within <10'	Loc. within <15'	Loc. within <20'
9	1.8%	27%	30%	37%
8	7.6%	26%	29%	33%
7	16%	5%	14%	19%
6	26%	2%	8%	13%
5	25%	1%	3%	8%
4	15%	1%	1%	1%

- ✓ ~12 % of Fermi-GBM sGRB: <20' localization accuracy
- ✓ Fermi GBM sGRB rate: 336 sGRBs/6 years ~ 60 sGRBs/year
- ✓ ~10 sGRBs/year for <20' localization accuracy with a timing-localization concept ! (0.5-1° for GRB170817A.. really??)
- ✓ Many things should be considered, observation efficiency, systematic uncertainties... etc. etc.